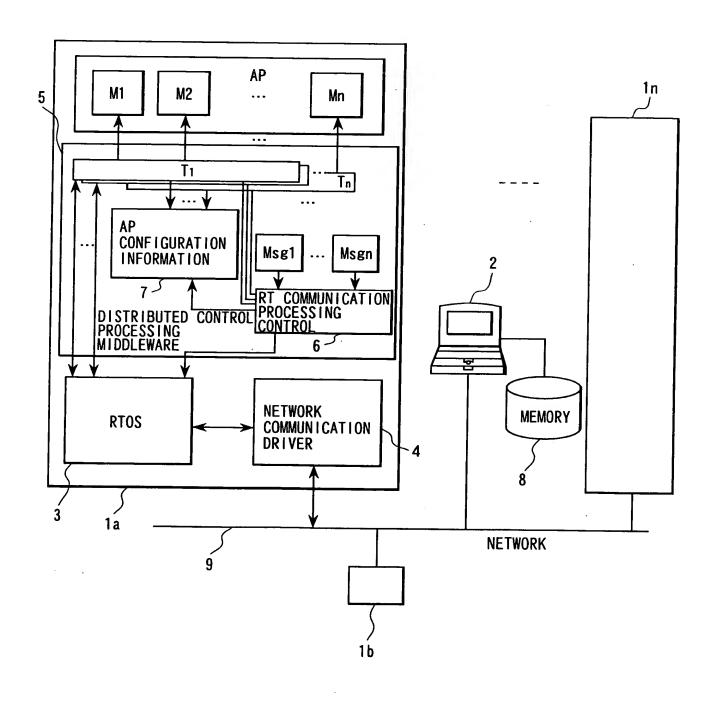
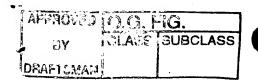
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FIG.1





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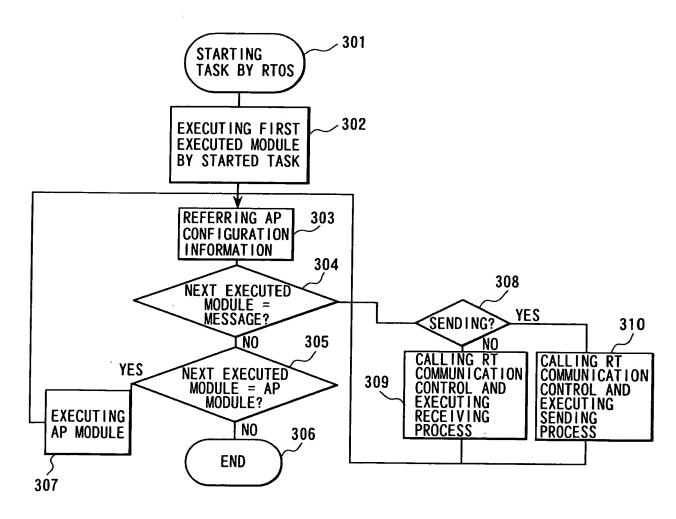
FIG.2

21a ر	_∫ 21b	_ 21
AP MODULE	NEXT EXECUTED MODULE	T
M1	Msg 1 SENDING	1
M2	М3]
M3	NULL]
M4	Msg 3 SENDING]
M5	NULL	
:		
Mn	NULL	j

22a		22c			22a 22
MESSAGE OBJECT NAME	PRIORITY OF COMMUNICATION PROCESSING	INTERNAL/ EXTERNAL COMMUNICATION	KIND OF COMMUNICATION SERVICE	AT SENDING	AT RECEIVING
Msg1	NULL	INTERNAL	INTERNAL	Msg1 RECEIVING	M2
Msg2	MIDDLE	EXTERNAL	EXTERNAL	NULL	M4
Msg3	LOW	EXTERNAL	EXTERNAL	M5	NULL
:		· :			
Msgm	HIGH	EXTERNAL	EXTERNAL	NULL	NULL

FIG.3

FLOW CHART SHOWING OPERATION OF MODULE STARTING CONTROL TASK



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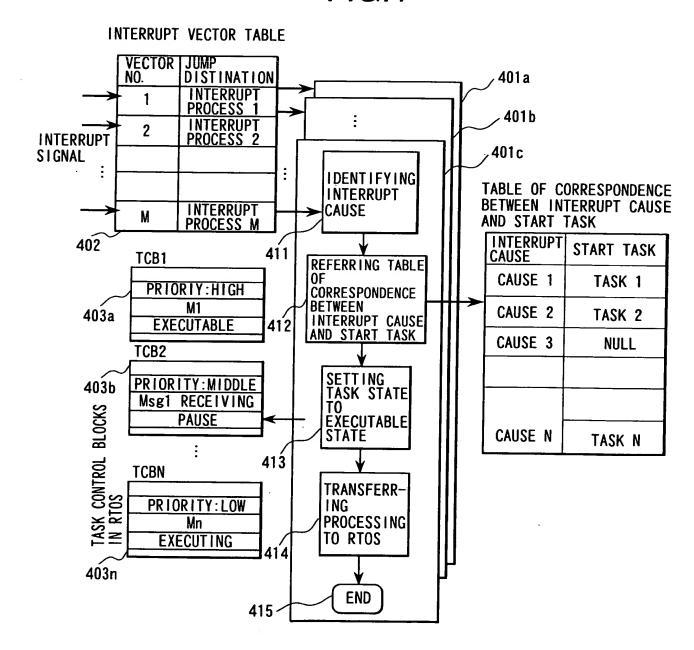
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FIG.4



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FIG.5

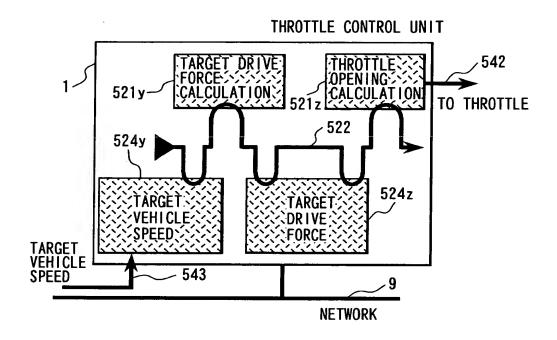
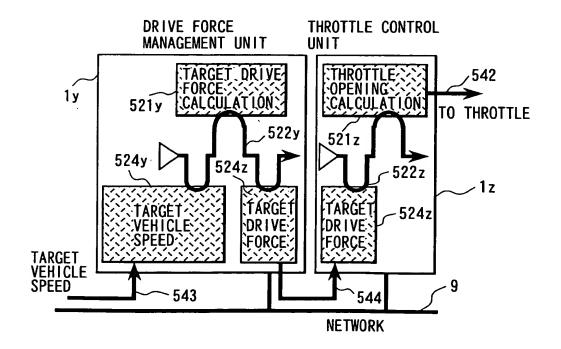


FIG.7



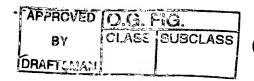


FIG.6(a)

INTERRUPT CAUSE	START TASK
30ms TIMER	MODULE START CONTROL TASK A

FIG.6(b)

PRIORITY:HIGH
RECEIVING TARGET VEHICLE SPEED

FIG.6(c)

AP MODULE	NEXT EXECUTED MODULE
TARGET DRIVE FORCE CALCULATION	TARGET DRIVE FROCE, SENDING
THROTTLE OPENING CALCULATION	NULL

FIG.6(d)

NEXT EXECUTED MODULE

MESSAGE OBJECT NAME	PRIORITY OF COMMUNICATION PROCESSING	INTERNAL/ EXTERNAL COMMUNICATION	KIND OF COMMUNICATION SERVICE	AT SENDING	AT RECEIVING
TARGET VEHICLE SPEED	MIDDLE	INTERNAL	ASYNCHRONOUS	NULL	TARGET DRIVE FORCE CALCULATION
TARGET DRIVE FORCE	NULL	INTERNAL	SYNCHRONOUS	TARGET DRIVE FORCE, SENDING	THROTTLE OPENING CALCULATION

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FIG.8(a)

INTERRUPT CAUSE	START TASK
30ms TIMER	TASK A

INTERRUPT CAUSE	START TASK	
TARGET DRIVE FORCE RECEIVING	TASK B	

FIG.8(b)

PRIORITY:HIGH
RECEIVING TARGET VEHICLE SPEED

\mid	PRIORITY: HIGH
	TARGET DRIVE FORCE RECEIVING

FIG.8(c)

AP MODULE	NEXT EXECUTED MODULE
TARGET DRIVE FORCE CALCULATION	TARGET DRIVE FROCE, SENDING
THROTTLE OPENING CALCULATION	NULL

FIG.8(d)

NEXT EXECUTED MODULE

	PRIORITY OF COMMUNICATION PROCESSING	INTERNAL/ EXTERNAL COMMUNICATION	KIND OF COMMUNICATION SERVICE	AT SENDING	AT RECEIVING
TARGET VEHICLE SPEED	MIDDLE	INTERNAL	ASYNCHRONOUS	NULL	TARGET DRIVE FORCE CALCULATION
TARGET DRIVE FORCE	HIGH	EXTERNAL	SYNCHRONOUS	NULL	THROTTLE OPENING CALCULATION

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F1G.9

PARAMETER CHANGE DUE TO ADDITION OF RADAR UNIT (FOLLOW-UP CONTROL)

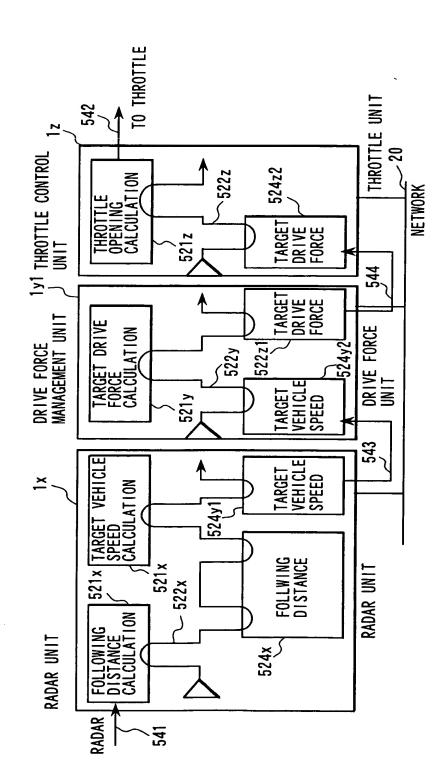


FIG.10

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT CAUSE AND START TASK IN DRIVE FORCE MANAGEMENT UNIT

INTERRUPT CAUSE	START TASK
TARGET VEHICLE SPEED RECEIVING	TASK A

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT AND START TASK IN THROTTLE CONTROL UNIT

INTERRUPT CAUSE	START TASK
TARGET DRIVE FORCE RECEIVING	TASK B

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT CAUSE AND START TASKIN DRIVE FORCE MANAGEMENT UNIT

INTERRUPT CAUSE	START TASK
30ms TAIMER	TASK C

FIG.11

TCB OF TASK A

PRIORITY: HIGH RECEIVING TARGET VEHICLE SPEED TCB OF TASK B

PRIORITY:HIGH TARGET DRIVE FORCE RECEIVING

TCB OF TASK C

PRIORITY:HIGH FOLLOWING DISTANCE CALCULATION

FIG.12

TABLE OF AP MODULE CONFIGURATION INFORMATION

AP MODULE	NEXT EXECUTED MODULE
TARGET DRIVE FORCE CALCULATION	TARGET DRIVE FORCE, SENDING
THROTTLE OPENING CALCULATION	NULL
FOLLOWING DISTANCE CALCULATION	FOLLOWING DISTANCE, SENDING
TARET VEHICLE SPEED CALCULATION	TARGET VEHICLE SPEED, SENDING

FIG.13

TABLE MESSAGE OBJECT CONFIGURATION INFORMATION

NEXT EXECUTED MODULE

MESSAGE OBJECT NAME	PRIORITY OF COMMUNICATION PROCESSING	INTERNAL/ EXTERNAL COMMUNICATION	KIND OF COMMUNICATION SERVICE	AT SENDING	AT RECEIVING
TARGET VEHICLE SPEED	MIDDLE	INTERNAL	SYNCHRONOUS	NULL	TARGET DRIVE FORCE CALCULATION
TARGET DRIVE FORCE	HIGH	EXTERNAL	SYNCHRONOUS	NULL	THROTTLE OPENING CALCULATION
FOLLOWING DISTANCE	NULL	INTERNAL	SYNCHRONOUS	FOLLOWING DISTANCE, RECEIVING	TARGET VEHICLE SPEED CALCULATION

FIG. 14

PARAMETER CHANGE DUE TO ADDITION OF RADAR UNIT (FOLLOW-UP CONTROL)

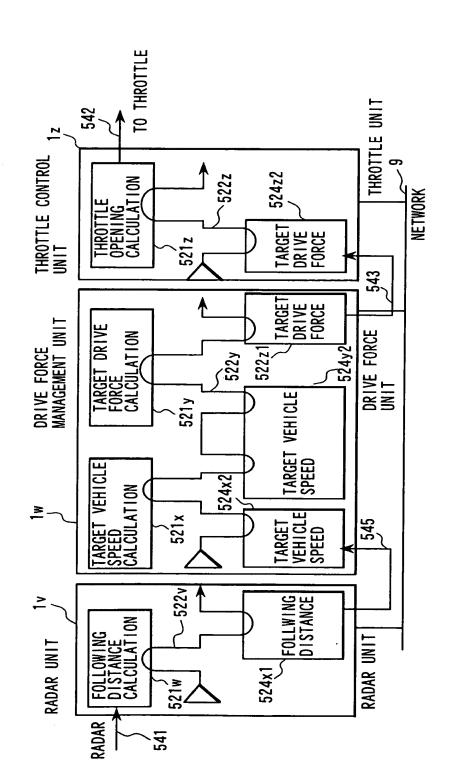




FIG.15

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT CAUSE AND START TASK IN DRIVE FORCE MANAGEMENT UNIT

INTERRUPT CAUSE	START TASK
FOLLOWING DISTANCE CALCULATION	TASK A

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT AND START TASK IN THROTTLE CONTROL UNIT

INTERRUPT CAUSE	START TASK
TARGET DRIVE FORCE RECEIVING	TASK B

TABLE OF CORRESPONDENCE BETWEEN INTERRUPT CAUSE AND START TASK IN DRIVE FORCE MANAGEMENT UNIT

INTERRUPT CAUSE	START TASK
30ms TAIMER	TASK C

FIG.16

TCB OF TASK A

PRIORITY:HIGH RECEIVING TARGET VEHICLE SPEED TCB OF TASK B

PRIORITY:HIGH TARGET DRIVE FORCE RECEIVING

TCB OF TASK C

PRIORITY:HIGH
FOLLOWING DISTANCE
CALCULATION

FIG.17

TABLE OF AP MODULE CONFIGURATION INFORMATION

AP MODULE	NEXT EXECUTED MODULE
TARGET DRIVE FORCE CALCULATION	TARGET DRIVE FORCE, SENDING
THROTTLE OPENING CALCULATION	NULL
FOLLOWING DISTANCE CALCULATION	FOLLOWING DISTANCE, SENDING
TARET VEHICLE SPEED CALCULATION	TARGET VEHICLE SPEED, SENDING

FIG.18

TABLE OF MESSAGE OBJECT CONFIGURATION INFORMATION

MESSAGE OBJECT NAME	PRIORITY OF COMMUNICATION PROCESSING	INTERNAL/ EXTERNAL COMMUNICATION	KIND OF COMMUNICATION SERVICE	AT SENDING NEXT EXEC	AT RECEIVING UTED MODULE
TARGET VEHICLE SPEED	MIDDLE	INTERNAL	SYNCHRONOUS	TARGET VEHICLE SPEED, RECEIVING	TARGET DRIVE FORCE CALCULATION
TARGET DRIVE FORCE	HIGH	EXTERNAL	SYNCHRONOUS	NULL	THROTTLE OPENING CALCULATION
FOLLOWING DISTANCE	NULL	INTERNAL	SYNCHRONOUS	FOLLOWING DISTANCE, RECEIVING	TARGET VEHICLE SPEED CALCULATION

FIG.19

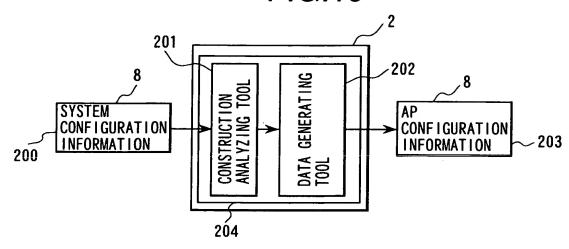


FIG.20

DISTRIBUTED CONTROL PROCESSING MIDDLEWARE CODE GENERATING TOOL

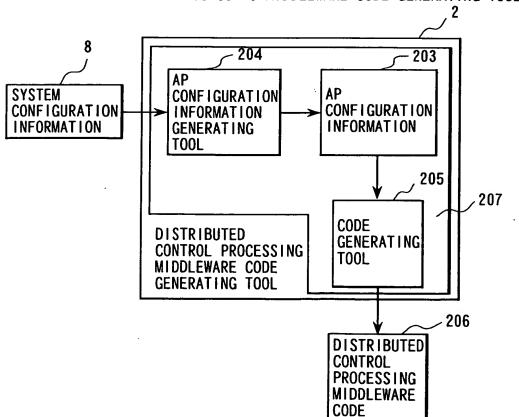
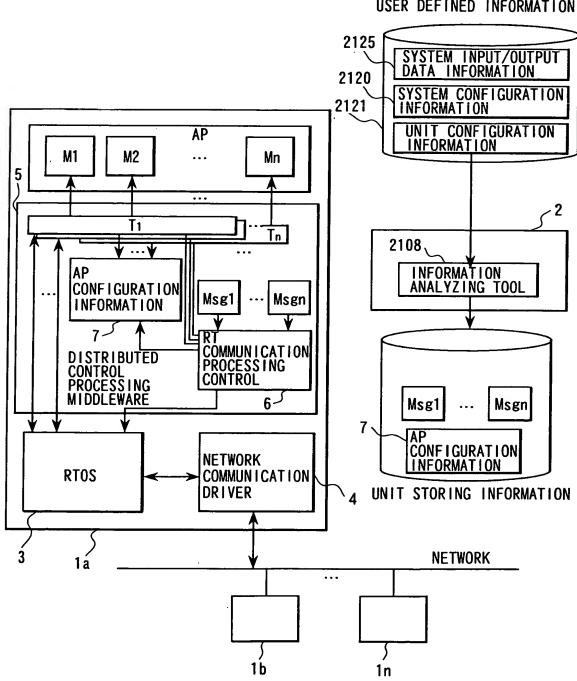


FIG.21

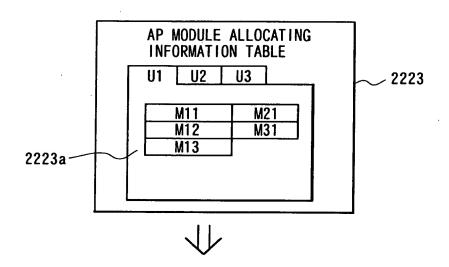
DISTRIBUTED CONTROL SYSTEM

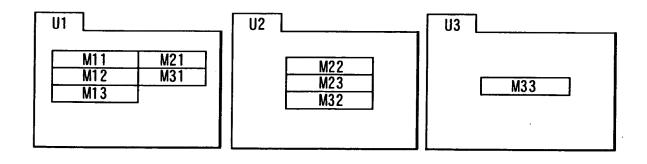
USER DEFINED INFORMATION



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FIG.22





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FIG.23

INPUT	OUTPUT
D11	D14
D21	D24
D31	D34

FIG.31

FLOW OF EXTRACTING COMMUNICATION DATA BETWEEN UNITS (\$3070)

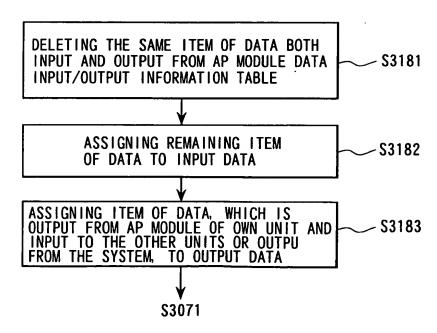
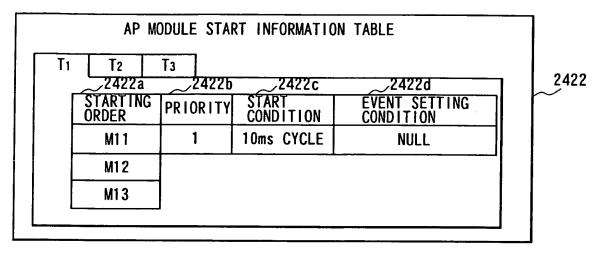


FIG.24



T1 ____

STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
M11	1	10ms CYCLE	NULL
M12			
M13			

T₂

STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
M11	2	AFTER UPDATING	1:10ms AFTER COMPLETION
M12		DATA D21	OF M22
WEIGHT 1			
M23			

T3

STÄRTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
M31	3	AFTER UPDATING	NULL
M32		DATA D22	NULL
M33]	·····	

FIG.25

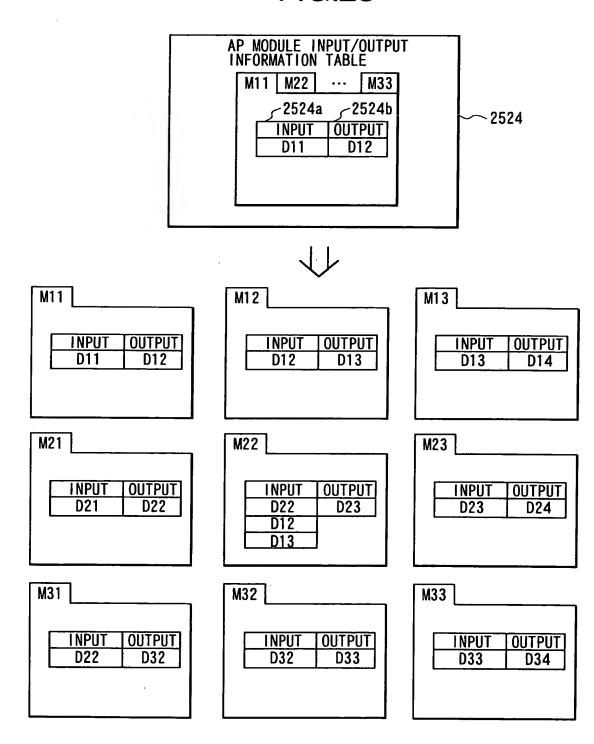


FIG.26(a)

AP MODULE/MESSAGE OBJECT START INFORMATION TABLE FOR UNIT1

T1					
	30a 🦯	-2630b	<u> </u>	ے <u>2630d</u>	
STAR ORDE	R	IORITY	START CONDITION	EVENT SETTI CONDITION	NG
Meg11 RECE	VING	1 1	Oms CYCLE	NULL	
M1	1				
M1	2				
Meg12 SEND	2-13 ING				
M1	3				

FIG.26(b)

T2				
	STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
	Meg21 RECEIVING	- 2	AFTER	NULL
	M21		UPDATING DATA Mge21	
	Meg22 SENDING			

FIG.26(c)

T3			
STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
Meg22 RECEIVING	3	AFTER	NULL
M31		ÚPĎÁŤING DATA Mge22	
Meg32 SENDING			
			· · · · · · · · · · · · · · · · · · ·

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FIG.27(a)

AP MODULE/MESSAGE OBJECT START INFORMATION TABLE FOR UNIT2

T ₂				•
	STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
	Meg22 RECEIVING Meg12-13 SENDING	1	AFTER UP DATING Meg22	1:10ms AFTER COMPLETING M22
	M22	_		
	WEIGHT 1			
	M23			
	Meg22 RECEIVING			

FIG.27(b)

Т3	<u> </u>			
ORDI		PRIORITY	START CONDITION	EVENT SETTING CONDITION
Meg3 RECE	2 IVING	2	AFTER UPDATING	NULL
	32		DATA Mge32	
Me g SEN	33 DING			
SEN	DING			

FIG.28

Тз			
STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
Meg33 RECEIVING	1	AFTER	NULL
M31		UPDATING DATA Mge33	NOLL
Meg34 SENDING	·		

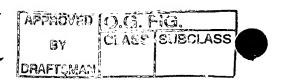


FIG.29(a)

DATA MESSAGE OBJECT READ/ WRITE SEND/ RECEIVE UPDATING CONDITION D11 Msg11 READ RECEIVING NULL NULL AFTER ARRIVAL D12 Msg12-13 WRITE SENDING NULL 2 AFTER M12 D14 Msg14 WRITE SENDING NULL 1 AFTER M13 D21 Msg21 READ RECEIVING TASK2 START NULL AFTER ARRIVAL D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21 D32 Msg32 WRITE SENDING NULL 2 AFTER M31		MES	SAGE OBJECT	INFORMATIO	N TABLE FOR	UNIT 1	
DATA OBJECT WRITE RECEIVE AFTER UPDATING CONDITION D11 Msg11 READ RECEIVING NULL AFTER ARRIVAL D12 Msg12-13 WRITE SENDING NULL 2 AFTER M12 D14 Msg14 WRITE SENDING NULL 1 AFTER M13 D21 Msg21 READ RECEIVING TASK2 START NULL AFTER ARRIVAL D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21	<u> 2931a ر _</u>	<u> 2931b ر</u>	<u>2931c ح</u>	ر 2931d		2931 f ر	ر 2931g
D12 Msg12-13 WRITE SENDING NULL 2 AFTER M12 D14 Msg14 WRITE SENDING NULL 1 AFTER M13 D21 Msg21 READ RECEIVING TASK2 START NULL AFTER ARRIVAL D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21	DATA				AFTER	PRIORITY	
D13 MSB12-13 WRITE SENDING NULL 2 AFTER M12 D14 Msg14 WRITE SENDING NULL 1 AFTER M13 D21 Msg21 READ RECEIVING TASK2 START NULL AFTER ARRIVAL D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21		Msg11	READ	RECEIVING	NULL	NULL	AFTER ARRIVAL
D21 Msg21 READ RECEIVING TASK2 START NULL AFTER ARRIVAL D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21	D12 D13	Msg12-13	WRITE	SENDING	NULL	. 2	AFTER M12
D22 Msg22 WRITE/READ SENDING TASK3 START 2 AFTER M21	D14	Msg14	WRITE	SENDING	NULL	1	AFTER M13
DOG IN OR HIDITE OFFICIAL	D21	Msg21	READ	RECEIVING	TASK2 START	NULL	AFTER ARRIVAL
D32 Msg32 WRITE SENDING NULL 2 AFTER M31	D22	Msg22	WRITE/READ	SENDING	TASK3 START	2	AFTER M21
THE THE PARTY OF T	D32	Msg32	WRITE	SENDING	NULL	2	AFTER M31

FIG.29(b)

DATA	MESSAGE OBJECT	READ/ WRITE	SEND/ RECEIVE	ACTION AFTER UPDATING	PRIORITY	UPDATING CONDITION
D22	Msg22	READ	RECEIVING	TASK2 START	NULL	AFTER ARRIVA
D12 D13	Msg12-13	READ	RECEIVING	NULL	NULL	AFTER ARRIVA
D24	Msg24	WRITE.	SENDING	NULL	2	AFTER M23
D32	Msg32	READ	RECEIVING	TASK3 START	NULL	AFTER ARRIVA
D33	Msg33	WRITE	SENDING	NULL	3	AFTER M32

FIG.29(c)

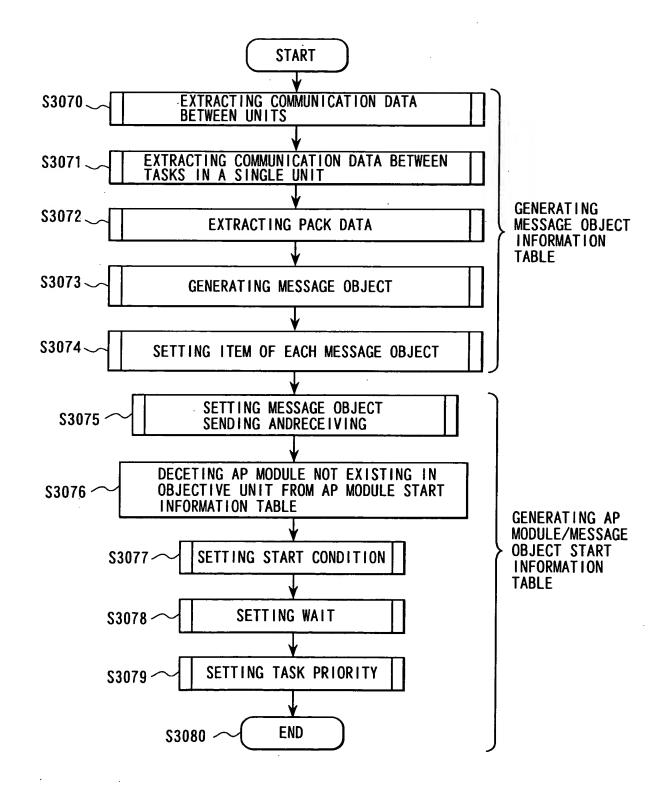
	MESS	SAGE OBJECT	INFORMATIO	N TABLE FOR	UNIT 3	
DATA	MESSAGE OBJECT	READ/ WRITE	SEND/ RECEIVE	ACTION AFTER UPDATING	PRIORITY	UPDATING CONDITION
D33	Msg22	READ	RECEIVING	TASK3 START	NULL	AFTER ARRIVA
D34	Msg24	WRITE	SENDING	NULL	2	AFTER M23

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FIG.30



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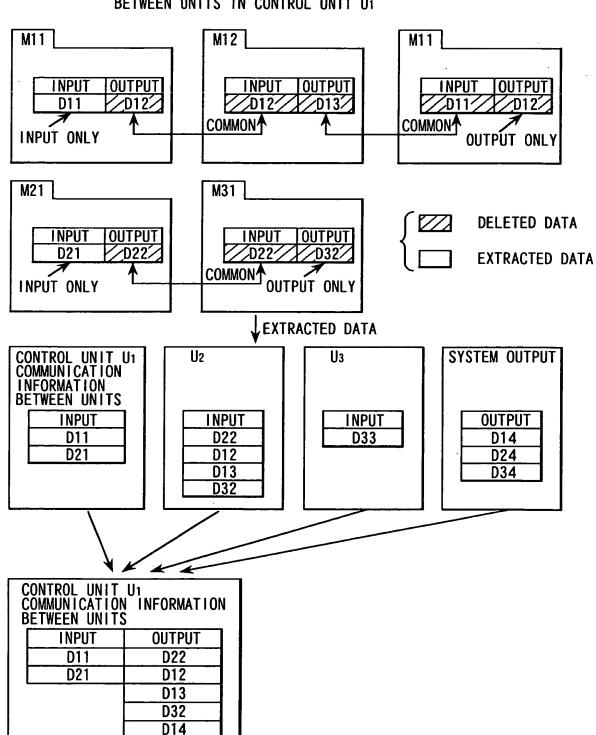
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FIG.32

PROCESSING OF EXTRACTING COMMUNICATION DATA BETWEEN UNITS IN CONTROL UNIT U1





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FIG.33

FLOW OF EXTRACTING COMMUNICATION DATA BETWEEN TASKS (\$3071)

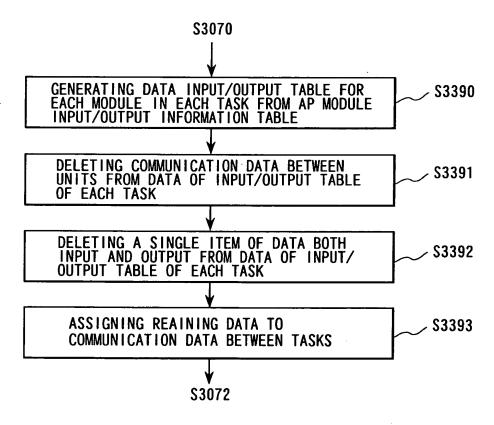
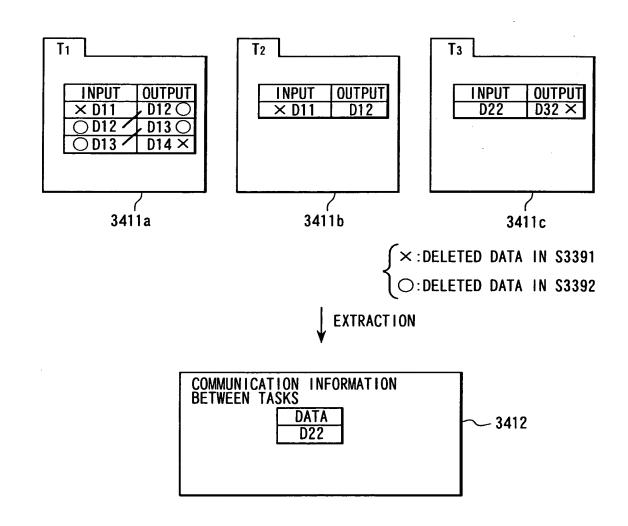




FIG.34

EXTRACTING COMMUNICATION DATA BETWEEN TASKS



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FIG.35

FLOW OF EXTRACTING DATA TO BE PACKED (\$3072)

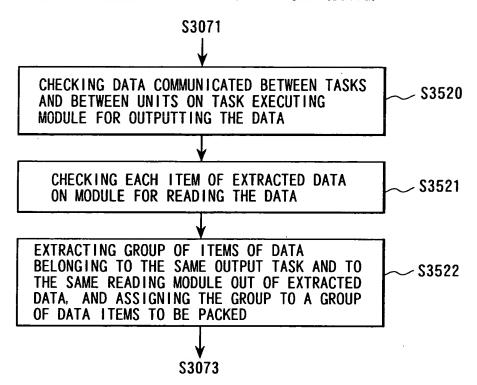


FIG.36

PACK EXTRACTING TABLE

	DATA	OUTPUT TASK	READING M	
	D22	T ₂	M31, M22	
	D11	_	M11	3630
	D21	-	M21	
	D14	T1		
	D32	Тз	_	7
PACK (D12	T1	M22	
LYCK (D13	T ₁	M22	7

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FIG.37

FLOW OF GENERATING MESSAGE OBJECT (S3073)

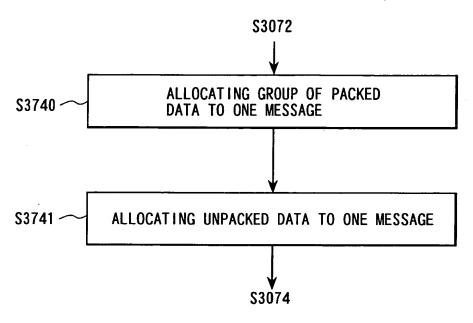
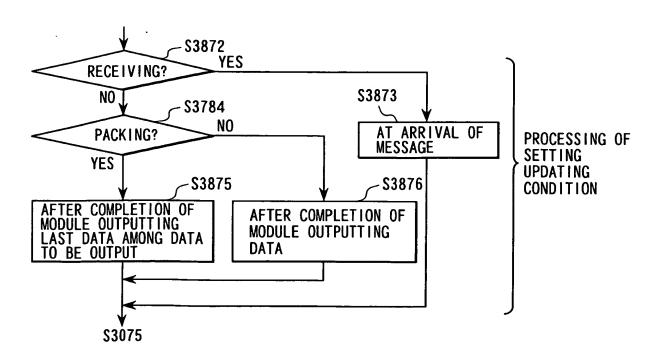


FIG.38

PROCESSING OF SETTING MESSAGE OBJECT ITEM (S3074)



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FIG.38

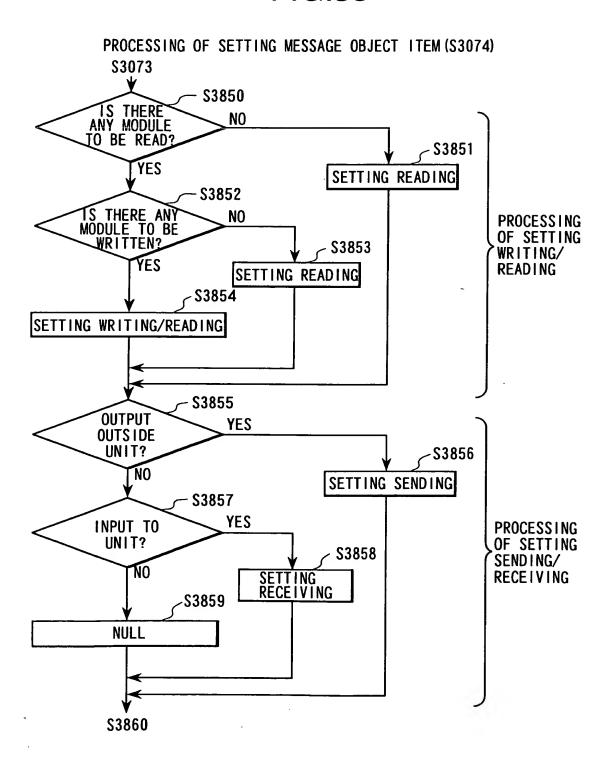
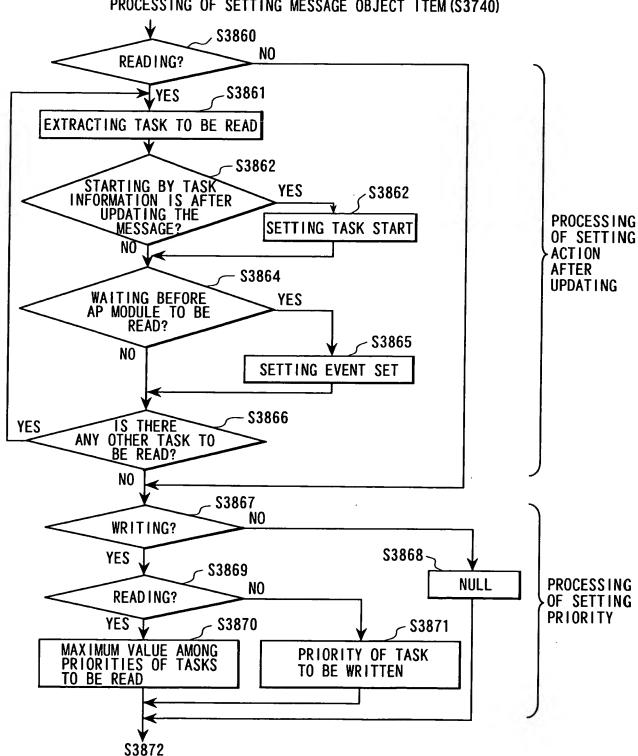


FIG.39

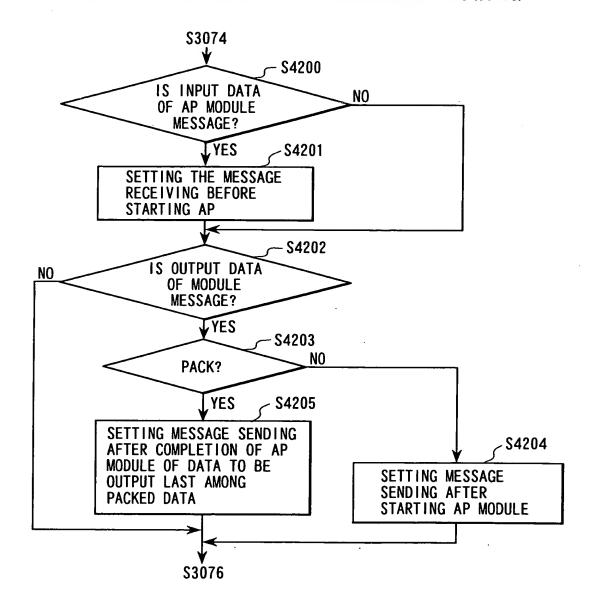
PROCESSING OF SETTING MESSAGE OBJECT ITEM (\$3740)



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FIG.41

FLOW OF SETTING MESSAGE OBJECT SENDING/RECEIVING (S3075)



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FIG.42

FLOW OF SETTING START CONDITION (3077)

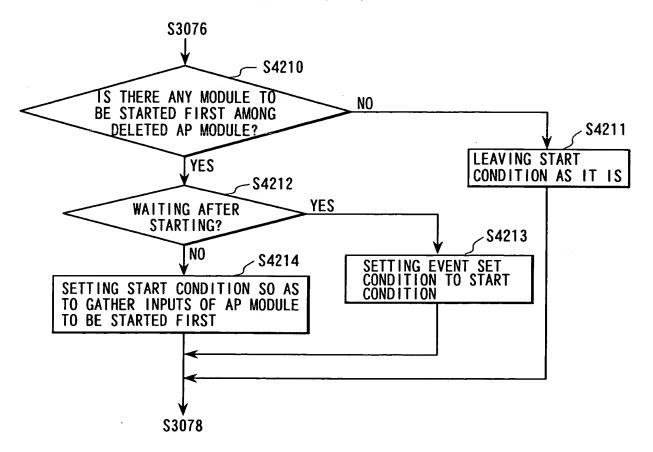


FIG.44

FLOW OF SETTING TASK PRIORITY (\$3079)

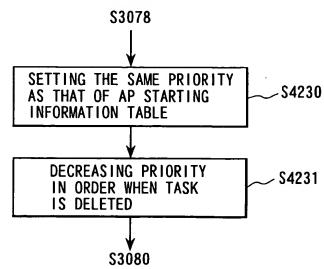
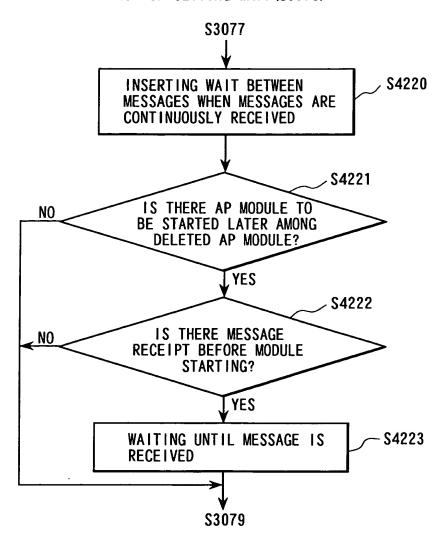


FIG.43

FLOW OF SETTING WAIT (S3078)



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FIG.45(a)

	7 4580h	Ack PRESENCE/ ABSENCE	PRESENCE	
	4580g	NOMSG START TASK ACALLOWABLE ID AT NUMBER OF CCURRENCE AE TIMES	TASK10	TASK10
ION TABLE	4580d 7 4580e 7 4580f 7 4580g	NOMSG ALLOWABLE NUMBER OF TIMES	10	10
IFORMAT		TIME- OUT	10	10
COMMUNICATION INFORMATION TABLE	1	ACTION AT TIME- RECEIVING OUT	+TASK3 Event set	+TASK2 EVENT SET
COMMU	4580a 7 4580b 7 4580c	DIRECT/ CYCLE (hour)	CYCLE (10) +TASK3 EVENT SET	ı
	a 74580b	DATA PRIORITY	3	1
	4580	DATA	D12	D23

FIG.45(b)

PACK INFORMATION TABLE	4581 j	SENDING COMMUNICATION TIMING ALONE	022	9N
	4581h _ 4581i	SENDING	AFTER UPDATING D12	ALL AFTER UPDATING ANY TIME AFTER UPDATING
	45811	Ack Presence/ Absence	-	ALL AFTER ANY TIME A
	4581a 7 4581b 7 4581c 7 4581d 7 4581e 7 4581f 7 4581g	ACTION AT TIME— ALLOWABLE ID AT PRESENCE/ RECEIVING OUT NUMBER OF OCCURRENCE ABSENCE	-	
		NOMSG ALLOWABLE NUMBER OF TIMES	l	
		TIME- OUT	. 1	
		ACTION AT RECEIVING	-	Ē
		DIRECT/ CYCLE (hour)	1	
		DATA PRIORITY	l	
	7 45	DATA	D12, D3, D22	



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FIG.46(a)

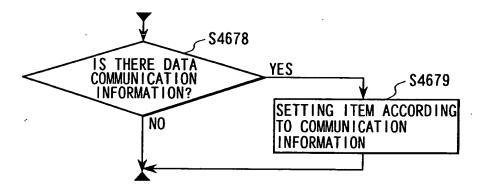
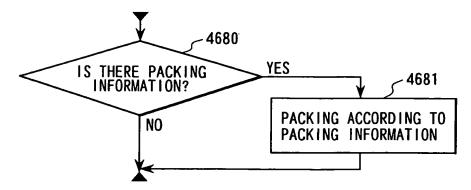


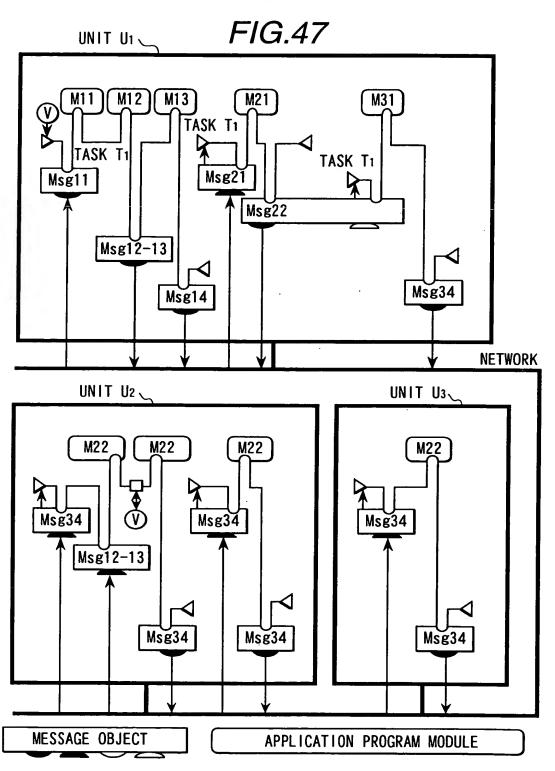
FIG.46(b)

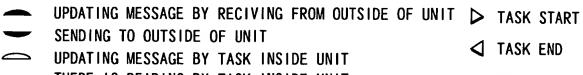


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36 / 53





THERE IS READING BY TASK INSIDE UNIT

☐ WAIT

FIG.48

MESSAGE OBJECT INFORMATION TABLE

DATA	MESSAGE	WRITE/ READ	SEND/ RECEIVE	ACTION AFTER UPDATING	PRIORITY	UPDATING CONDITION	
D12	Msg12-13	WRITE/	All II		2	ACTED M10	
D13	M2817-12	READ	NULL	NULL	2	AFTER M12	
D22	Msg22	WRITE/READ	NULL	TASK3 START	3	AFTER M21	
D11	Msg11	READ	RECEIVE	NULL	NULL	AFTER ARRIVA	
D21	Msg21	READ	RECEIVE	TASK2 START	NULL	AFTER ARRIVAL	
D14	Msg14	WRITE	SEND	NULL	1	AFTER M13	
D24	Msg24	WRITE	SEND	NULL	2	AFTER M23	
D34	Msg34	WRITE	SEND	NULL	3	AFTER M33	

Blue, Perry Blow, B. B. Sand, B. B. T. Annell Steam Blow, B. B. R. & Ten Bress, B. B. Ten Prop. B. Te

FIG.49

EXAMPLE OF AP MODULE/MESSAGE OBJECT START INFORMATION TABLE

TASK	1	

STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
Meg11 RECEIVING	1	10ms CYCLE	NULL
M1 1			
M12			
Meg12-13 SENDING			
M13			·
Meg12-13 SENDING			

TASK 2

STARTING ORDER	PRIORITY	CONDITION	EVENT SETTING CONDITION
Meg21 RECEIVING	2	AFTER UPDATING	1:10ms AFTER
M21		Meg21	COMPLETION OF M22
Meg22 SENDING	· •	, , , , , , , , , , , , , , , , , , ,	
Meg12-13 SENDING			
M22			
WEIGHTING 1			
M23			
+			

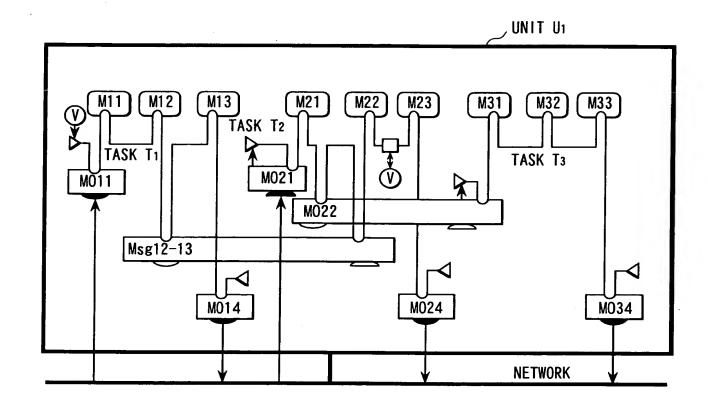
TASK 3

STARTING ORDER	PRIORITY	START CONDITION	EVENT SETTING CONDITION
Meg22 RECEIVING	3	AFTER UPDATING	Allete d
M31		Meg22	NULL
M32			
M33			
Meg34 RECEIVING			

Sand them to the the three first the them.

39 / 53

FIG.50



MESSAGE OBJECT

APPLICATION PROGRAM MODULE

- UPDATING MESSAGE BY RECIVING FROM OUTSIDE OF UNIT
- SENDING TO OUTSIDE OF UNIT
- UPDATING MESSAGE BY TASK INSIDE UNIT
- THERE IS READING BY TASK INSIDE UNIT
- > TASK START
- **✓** TASK END
- □ WAIT

40 / 53

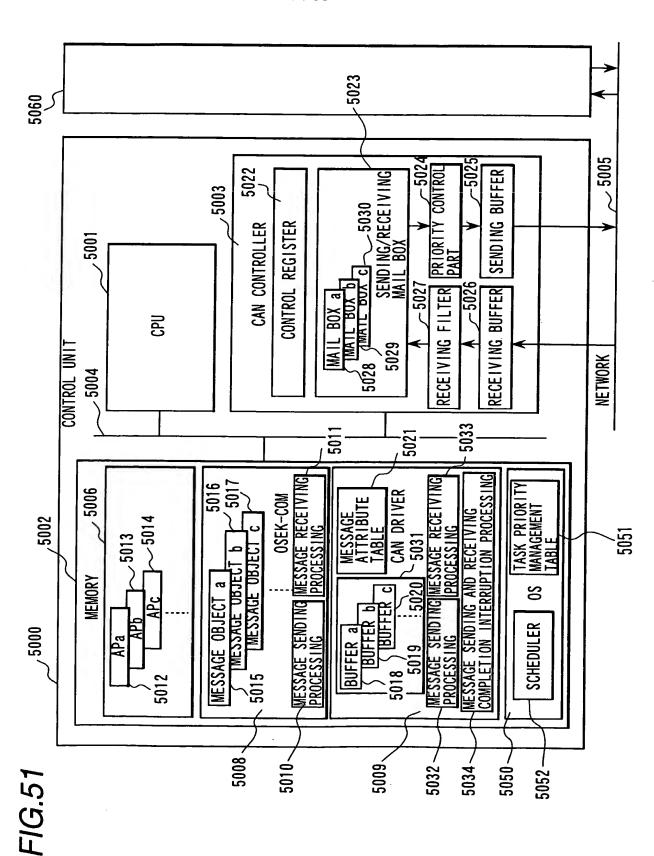




FIG.52

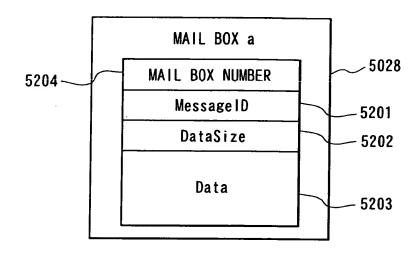
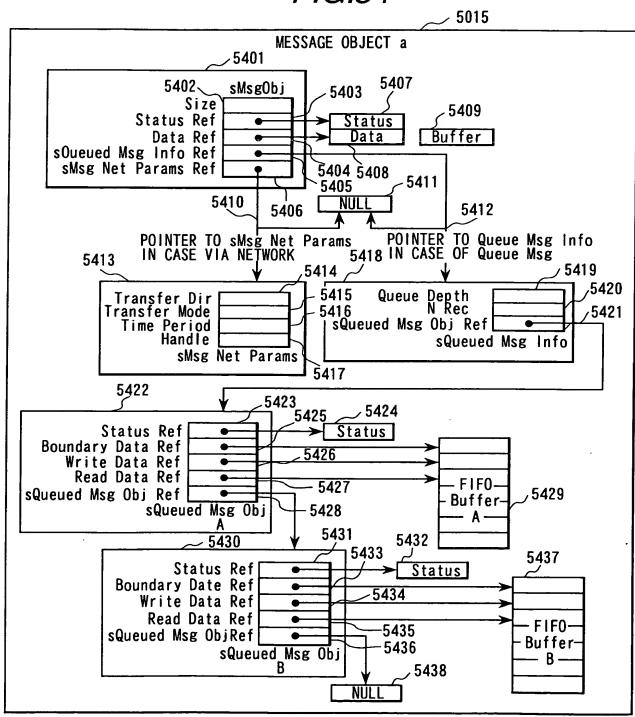


FIG.53

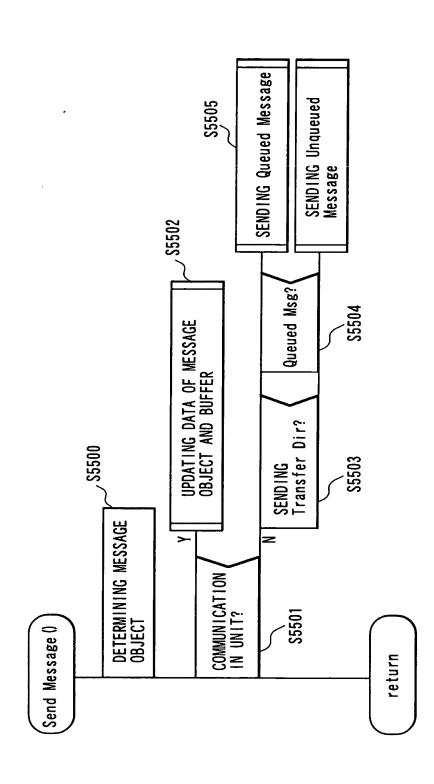
			(5 022 _/			
	CONTROL REGISTER						
5301 	53 0	02 530	530	5305			
MAIL BOX NUMBER	TXPR	TXACK	RXPR	MBIMR			
0	0	0	0	0			
1	1	1	1	1			
2	2	2	2	2			
•	•	•	•	•			
•	•	•	•	•			

FIG.54



The part of the pa

43 / 53



Bong, Dong, Hong, Hon Walt H H ... and Mann H I H J. Then Done II H and State State II H and State State II H and State State

FIG.55

Harry H. H. H. P. Tran Born B. D. and B. D. and B. D. Trans Reserving Trans. Trans. Trans.

17,

Horr, Born Born, H. & Barly B. W.

44 / 53

FIG.56

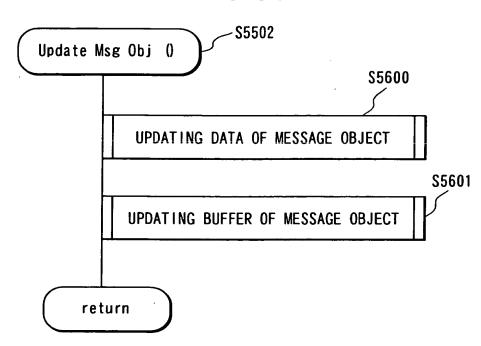
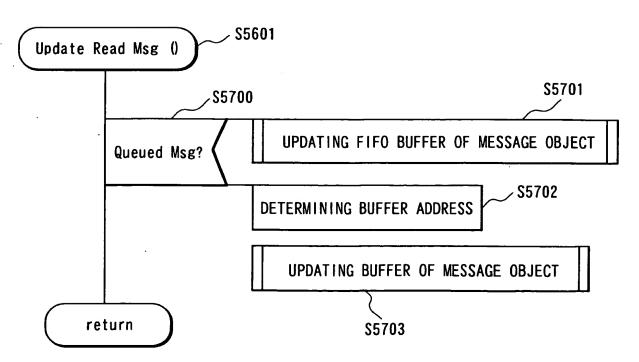
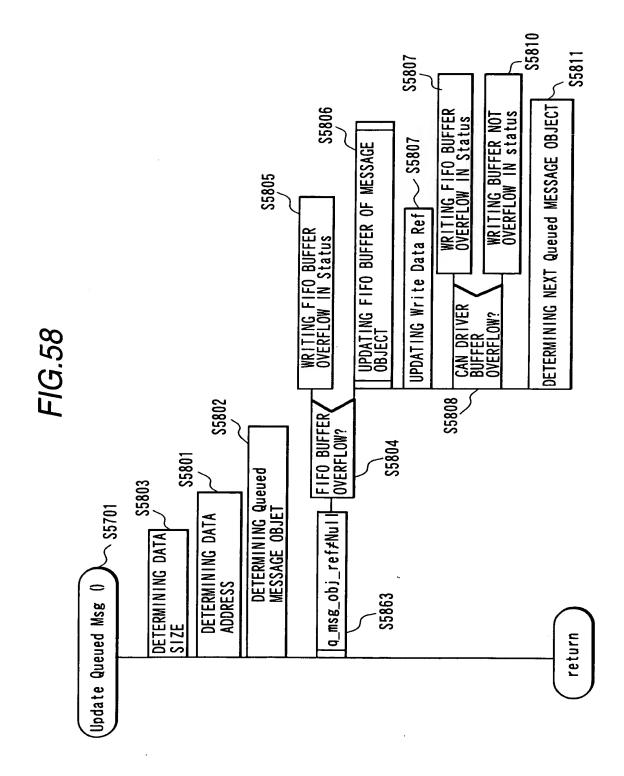


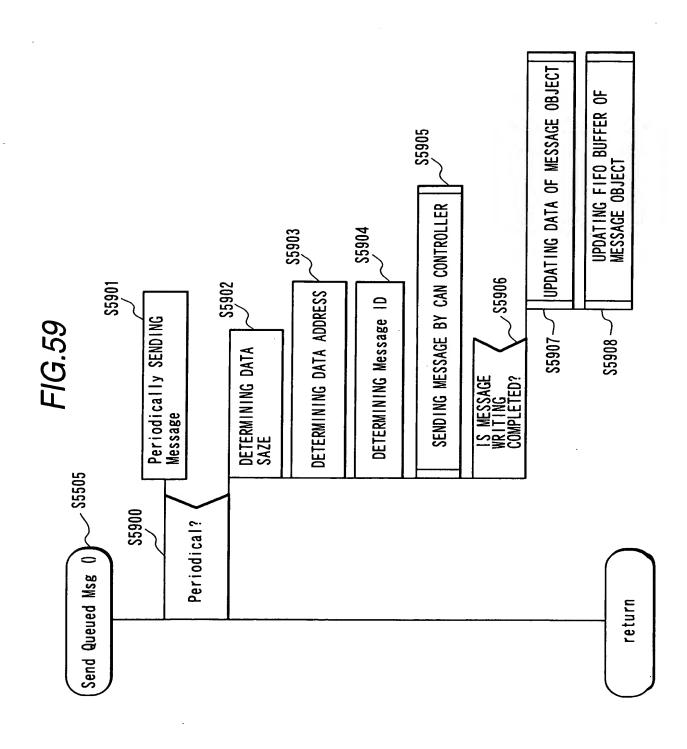
FIG.57

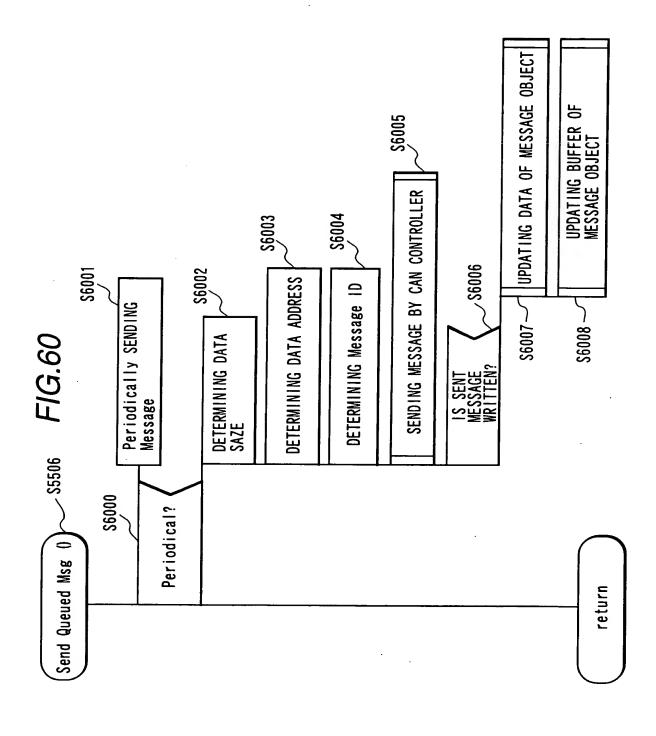


45 / 53

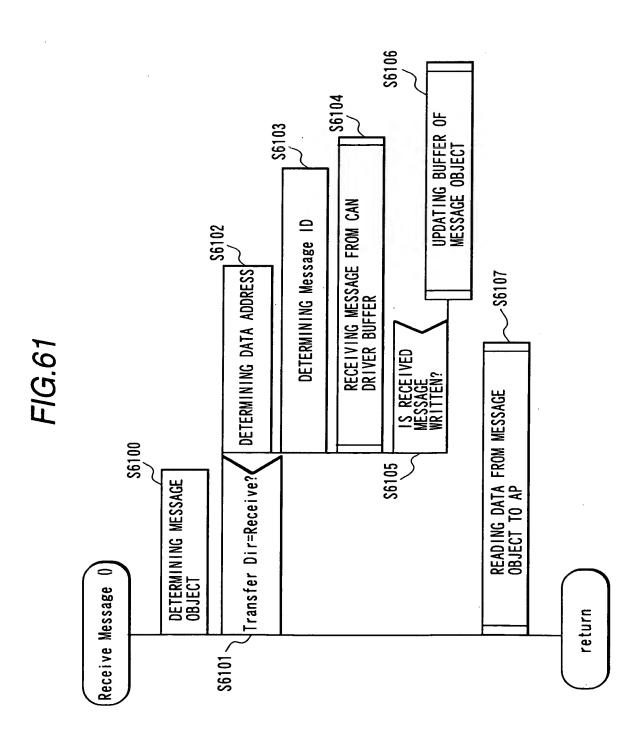


46 / 53



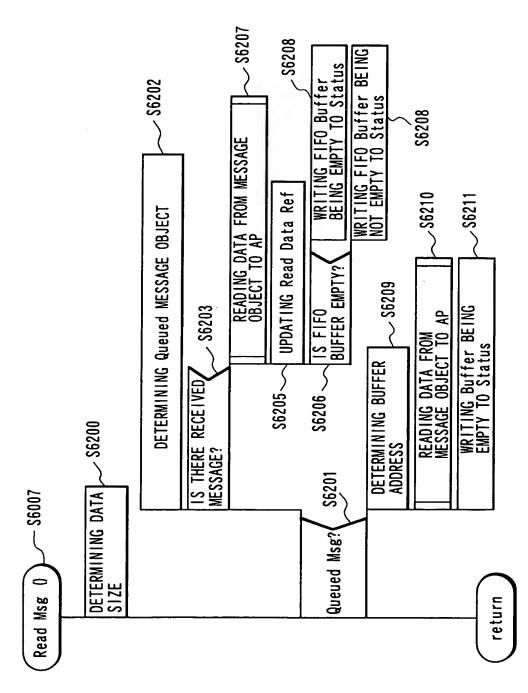


48 / 53



Horse Blook Horse H. 19 April H. H. . . and Mann. H. H. H. J. Phan. Book H. H. Horse H. H. Horse Tarde Tarde





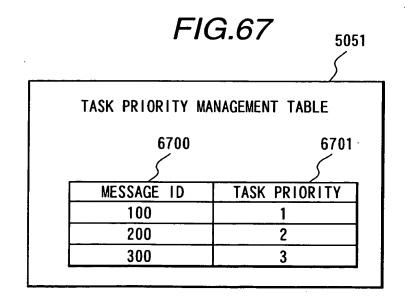


Davis Davis

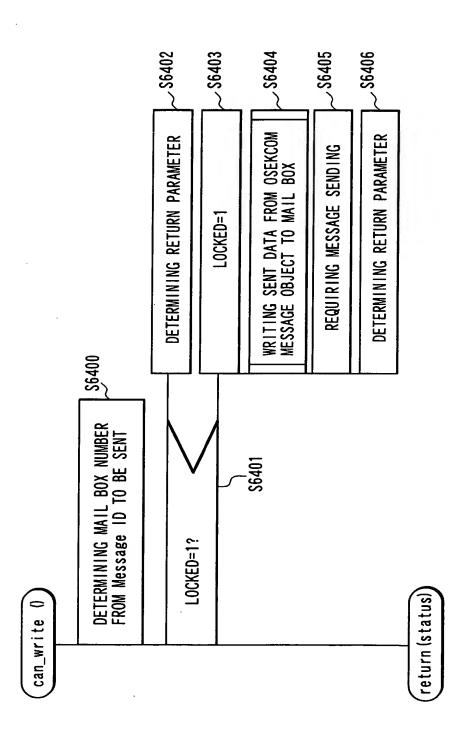
50 / 53

FIG.63

	MESSAGE ATTRIBUTE TABLE							
	6301 لے	6302 ر	6303 رس	6304 ر	6305 ر	6306 كىر	6307 كى	
MAIL BOX	NUMBER	Message ID	Data Size	QUEUED	LOCKED	NOMSG	LIMIT	
0		100	8	0	- 1	1	0	
1		200	8	1	0	1	0	
2		500	8	0	0	1	0	
•	·	•	•	•	•	•	•	
•		•	•	•	•	•		



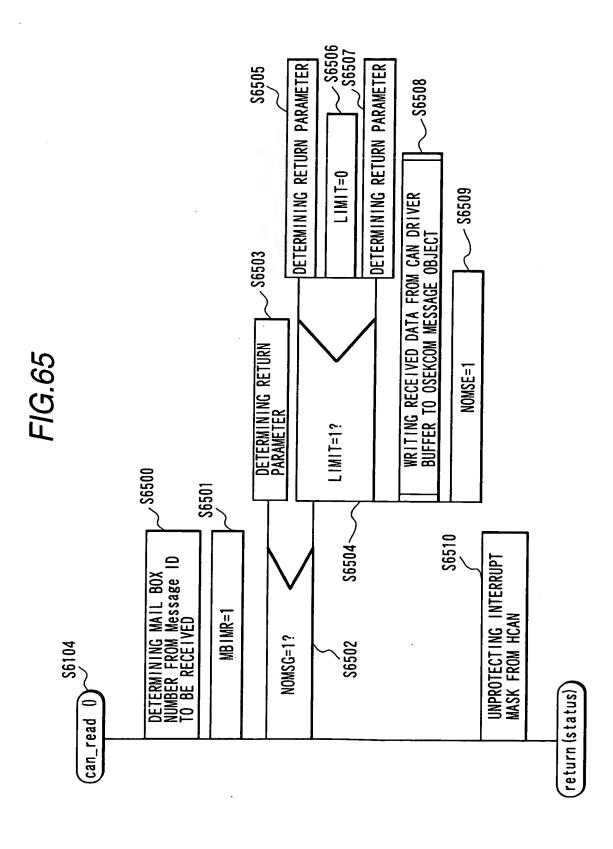
51 / 53



Heat State lives if B that H is a condition in H is a live H is a

FIG.64





Rain, Brein, Bre

